Lecture 3-2: General-Purpose Machine Tools: Drilling Machines and Operations

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Drilling and Drilling Allied Operations Drilling Operation Drilling is a process used extensively by which through or blind holes are originated or enlarged in a WP. This process involves feeding a rotating cutting tool (drill) along its axis of rotation into a stationary WP (Figure 3.15). The axial feed rate f is usually very small when compared to the peripheral speed v. Drilling is considered a roughing operation and, therefore, the accuracy and surface finish in drilling are generally not of much concern. If high accuracy and good finish are required, drilling must be followed by some other operation such as reaming, boring, or grinding.

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GENERAL-PURPOSE DRILLING MACHINES • Cutting movements. • As shown in the gearing diagram (Figure 3.23), the kinematic chain equations for the maximum spindle speed and feed are given by $n_{max} = 1420 \cdot \frac{27}{27} \cdot \frac{33}{33} \cdot \frac{52}{26} = 2840 \text{ rpm}$ $f_{max} = 1 \cdot \frac{22}{42} \cdot \frac{24}{24} \cdot \frac{32}{21} \cdot \frac{17}{44} \cdot \frac{1}{60} \times \pi \times 2.5 \times 14 = 0.56 \text{ mm/rev}$

- Auxiliary movements.
- The drill head, housing the speed and feed gearboxes, moves along the machine column through the gear train: worm gearing 1/20-rack and pinion (z = 14, m = 2). The machine table can be moved vertically by hand through bevels 18/45 and an elevating screw driven by means of a handle (Figure 3.23).

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GENERAL-PURPOSE DRILLING MACHINES

- Radial Drilling Machines.
- These machines are especially designed for drilling, counterboring, countersinking, reaming, and tapping holes in heavy and bulky WPs that are inconvenient or impossible to machine on the upright drilling machines. They are suitable for multitool machining in individual and batch production.

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- Radial drilling machines (Figure 3.24) differ from upright drill presses in that the spindle axis is made to coincide with the axis of the hole being machined by moving the spindle in a system of polar coordinate to the hole, while the work is stationary.
- This is achieved by:
 - 1. Swinging the radial arm (4) about the rigid column (2)
 - 2. Raising or lowering the radial arm on the column by the arm-elevating and -clamping mechanism (3) to accommodate the WP height
 - 3. Moving the spindle head (5) along the guideways of the radial arm (4)

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- Accordingly, the tool is located at any required point on the stationary WP, which is set either on detachable table (6) or directly on base (1).
- After the maneuvering tasks performed by the radial arm and spindle head, they are held in position using power-operated clamping devices.
- The spindle head gearing diagram of the radial drilling machine is very similar to that of the upright drill press.

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GENERAL-PURPOSE DRILLING MACHINES

- Multispindle Drilling Machines.
- These are mainly used in lot production for machining WPs requiring simultaneous drilling, reaming, and tapping of a large number of holes in different planes of the WP.
- A single spindle drilling machine is not economical for such purposes, as not only a considerably large number of machines and operators are required but also the machining cycle is longer.

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- There are three types of multiplespindle drilling machines: a. Gang multispindle drilling machines.
 - The spindles (2–6) are arranged in a row, and each spindle is driven by its own motor.
 - The gang machine is in fact several upright drilling machines having a common base and single worktable (Figure 3.25). They are used for consecutive machining of different holes in one WP, or for the machining of a single hole with different cutting tools.

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They are, as a rule, chiefly built of standard units. Such machines are designed for machining a definite component held in a jig and are frequently built into an automatic transfer machine (Figure 3.27).

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