

Sharif University of Technology
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Computational Fluid Dynamics

Classification of PDEs

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Classification

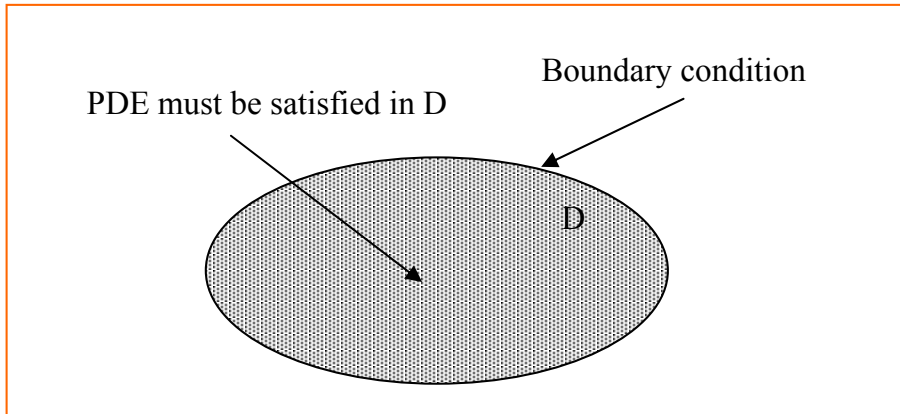
- Classification of PDEs helps us to understand their behavior and choose suitable solution techniques.
- Classification of the governing equations can be performed in two ways:
 - Mathematical
 - physical
- PDEs are categorized in terms of **mathematical** types as follows:
 - Hyperbolic (wave)
 - Parabolic (transient heat-conduction)
 - Elliptic (diffusion)
- PDEs are categorize in terms of **physical** types as follows:
 - Equilibrium Problems (steady heat conduction)
 - Marching Problems (Unsteady heat conduction)

Physical Classification

- Equilibrium problems involve a closed domain and boundary conditions.
- They are in fact boundary value problems.
- Examples are **Laplace** and **Poisson** equations:

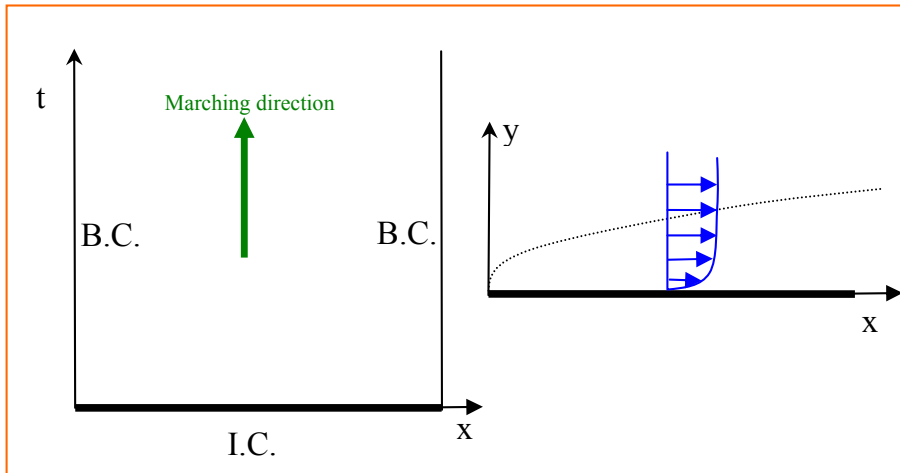
$$\nabla^2 \phi = 0$$

$$\nabla^2 p = f(u, v, \nabla \cdot \mathbf{V})$$



Physical Classification...

- Marching problems involve an open domain (time or time-like) and initial conditions and/or boundary conditions.
- Example are unsteady heat conduction and boundary layer (without separation) problems.



Physical Classification...

- **Boundary layer equations:** (marching in x-direction)

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$
$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \nu \frac{\partial^2 u}{\partial y^2}$$

- **Pure initial value problems:**

$$I.C. \quad u(x,0) = f(x) \quad \rightarrow \quad \begin{cases} \frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0 & \text{linear Berger Eq.} \\ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0 & \text{non-linear Berger Eq.} \end{cases}$$

$$I.C. \quad u(x,0) = f(x) \quad \& \quad u_t(x,0) = g(x)$$
$$\rightarrow \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} \quad (\text{wave Eq.})$$

Mathematical Classification

- Consider the following general 2nd order PDE:

$$A\varphi_{xx} + B\varphi_{xy} + C\varphi_{yy} + D\varphi_x + E\varphi_y + F\varphi + G = 0$$

- The characteristic equation of this PDE is:

$$A\left(\frac{dy}{dx}\right)^2 - B\left(\frac{dy}{dx}\right) - C = 0$$

- Whose roots are:

$$\left(\frac{dy}{dx}\right) = \frac{B \pm \sqrt{B^2 - 4AC}}{2A}$$

- We can categorize the PDE according to its discriminant: $D = B^2 - 4AC$

Mathematical Classification...

- If $D > 0$ at $p(x_0, y_0)$, two real characteristics exist and the equation is **Hyperbolic**.
- If $D = 0$ at $p(x_0, y_0)$, only one real characteristic exists and the equation is **Parabolic**.
- If $D < 0$ at $p(x_0, y_0)$, no real characteristics exist and the equation is **elliptic**.
- If D changes sign then the PDE is of **mixed** type. For example, for 2D potential flow and Transonic flow, we have:

$$(1 - M^2)\varphi_{xx} + \varphi_{yy} = 0$$

$$D = -4(1 - M^2)$$

- Note that a PDE can be of different types in different regions.

Mathematical Classification...

- Wave equation:

$$\begin{array}{l} u_{tt} = a^2 u_{xx} \quad , \\ I.C.: \quad u(x,0) = f(x), \quad u_t(x,0) = g(x) \end{array}$$

- The exact solution is

$$u(x,t) = \frac{1}{2} [f(x+at) + f(x-at)] + \frac{1}{2a} \int_{x-at}^{x+at} g(z) dz$$

- It is seen that

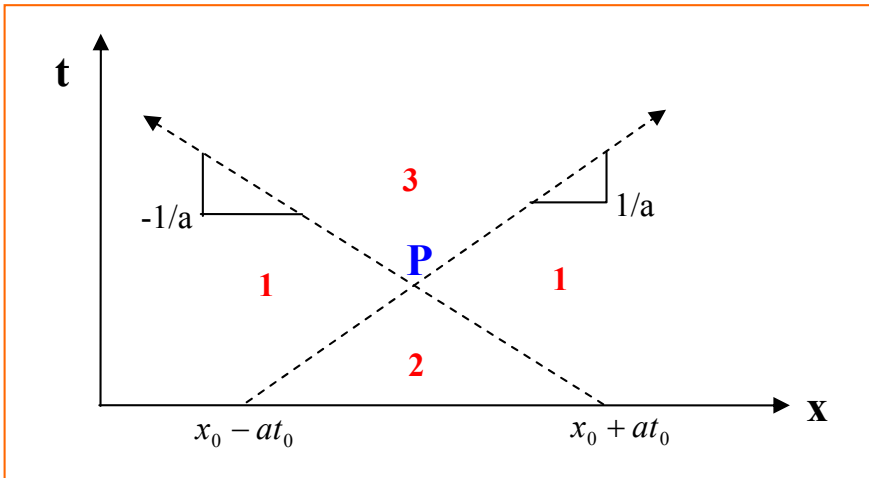
$$D = 4a^2 \quad \rightarrow \quad \textit{Hyperbolic}$$

- On the $x-t$ plane, we can show that two characteristic lines exist

$$\frac{dt}{dx} = \pm \frac{1}{a} \quad \rightarrow \quad \begin{cases} x = at + c_1 \\ x = -at + c_2 \end{cases}$$

Mathematical Classification...

- Region 3 is called domain of influence for point P .
- Region 2 is called domain (zone) of dependence for point P .
- Region 1, is called domain of silence. This region does not feel the other two regions.



Model Equations

- **Laplace and Poisson:**

$$\varphi_{xx} + \varphi_{yy} = \begin{cases} 0 \\ f(x, y) \end{cases}$$

- **Unsteady Heat Conduction:**

$$\varphi_t = \alpha(\varphi_{xx} + \varphi_{yy})$$

- **First order linear wave equation (Linear Burger Eq.):**

$$\varphi_t + a\varphi_x = 0$$

- **First order nonlinear wave equation (Inviscid nonlinear burger):**

$$\varphi_t + \varphi\varphi_x = 0$$

- **Viscous Burger Equation:**

$$\varphi_t + \varphi\varphi_x = \nu\varphi_{xx}$$

- **Second order wave equation:**

$$\varphi_{tt} = a^2\varphi_{xx}$$

System of PDEs

- In general, any higher-order PDE can be converted to a system of first order PDEs.

- EXAMPLE:** Let us consider the wave equation $\varphi_{tt} = a^2 \varphi_{xx}$:

$$\left\{ \begin{array}{l} v = \frac{\partial u}{\partial t} \\ w = a \frac{\partial u}{\partial x} \end{array} \right. \rightarrow \left\{ \begin{array}{l} \frac{\partial v}{\partial t} = \frac{\partial^2 v}{\partial t^2} \\ \frac{\partial v}{\partial x} = \frac{\partial^2 u}{\partial t \partial x} \\ \frac{\partial w}{\partial x} = a \frac{\partial^2 u}{\partial x^2} \\ \frac{\partial w}{\partial t} = a \frac{\partial^2 u}{\partial x \partial t} \end{array} \right. \rightarrow \frac{\partial}{\partial t} \begin{bmatrix} v \\ w \end{bmatrix} + \begin{bmatrix} 0 & -a \\ -a & 0 \end{bmatrix} \frac{\partial}{\partial x} \begin{bmatrix} v \\ w \end{bmatrix} = 0$$

- Or equivalently

$$\frac{\partial \mathbf{U}}{\partial t} + \mathbf{A} \frac{\partial \mathbf{U}}{\partial x} = \mathbf{0}$$

- Eigen-values of \mathbf{A} are $\lambda = \pm a$.
- Therefore, we have two distinct real eigen-value.
- That is our system is **Hyperbolic**.

System of PDEs...

- **EXAMPLE:** studying the Laplace equation, $\varphi_{xx} + \varphi_{yy} = 0$, we

find:

$$\begin{cases} u = \frac{\partial \varphi}{\partial y} \\ v = \frac{\partial \varphi}{\partial x} \end{cases} \rightarrow \frac{\partial}{\partial x} \begin{bmatrix} u \\ v \end{bmatrix} + \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \frac{\partial}{\partial y} \begin{bmatrix} u \\ v \end{bmatrix} = 0$$

- This has two distinct complex eigen-values, $\lambda = \pm i$.
- Therefore, the equation is **elliptic**.

Linear Unsteady System of Equations

- Consider

$$\frac{\partial \varphi}{\partial t} + A \frac{\partial \varphi}{\partial x} + B \frac{\partial \varphi}{\partial y} + \psi = 0$$

- Here, matrices A and B are functions of t, x and y .
- φ is a column vector and is the dependent variable.
- ψ is a column vector and is function of φ, x and y .
- The equation is **hyperbolic** at a point $p(x, t)$ if the eigen-values of A are all real and distinct.
- The equation is **hyperbolic** at a point $p(y, t)$ if the eigen-values of B are all real and distinct.
- The equation is **parabolic** at a point $p(x, t)$ if the eigen-values of A are all real but less than number of equations.
- The equation is **parabolic** at a point $p(y, t)$ if the eigen-values of B are all real but less than number of equations.

Linear Unsteady System of Equations

- The equation is **elliptic** at a point $p(x,t)$ if the eigen-values of A are all complex.
- The equation is **elliptic** at a point $p(y,t)$ if the eigen-values of B are all complex.
- The equation is **mixed (Hyperbolic/Elliptic)** at a point $p(x,t)$ if the eigen-values of A are mixed real and complex.
- The equation is **mixed (Hyperbolic/Elliptic)** at a point $p(y,t)$ if the eigen-values of B are mixed real and complex.

Linear Steady System of Equations

- Consider

$$A \frac{\partial \varphi}{\partial x} + B \frac{\partial \varphi}{\partial y} + \psi = 0$$

- Method 1:** define

$$H = R^2 - 4PQ$$

where

$$P = |A| \quad Q = |B| \quad R = \begin{vmatrix} a_1 & a_4 \\ b_1 & b_4 \end{vmatrix} + \begin{vmatrix} a_3 & a_2 \\ b_3 & b_2 \end{vmatrix}$$

- Then,

$$\begin{array}{ll} H > 0 & \rightarrow \text{Hyperbolic} \\ H = 0 & \rightarrow \text{parabolic} \\ H < 0 & \rightarrow \text{Elliptic} \end{array}$$

- Method 2:** re-write the equation as

$$(A\hat{i} + B\hat{j}) \cdot \left(\frac{\partial \varphi}{\partial x} \hat{i} + \frac{\partial \varphi}{\partial y} \hat{j} \right) + \psi = 0$$

Linear Steady System of Equations

- In the characteristic direction \vec{n} , we can write

$$T = (A\hat{i} + B\hat{j}) \cdot (n_x\hat{i} + n_y\hat{j}) = An_x + Bn_y$$

- A wave-like solution will exist if

$$|T| = 0 \quad \text{or} \quad |An_x + Bn_y| = 0$$

- This gives

$$Q\left(\frac{n_x}{n_y}\right)^2 + R\left(\frac{n_x}{n_y}\right) + P = 0$$

- Or ($H = R^2 - 4PQ$)

$$\frac{n_x}{n_y} = \frac{-R \pm \sqrt{H}}{2Q}$$

- Therefore,

$$H > 0 \rightarrow \text{Hyperbolic}$$

$$H = 0 \rightarrow \text{Parabolic}$$

$$H < 0 \rightarrow \text{Elliptic}$$

Linear Steady System of Equations

- **EXAMPLE:** Steady, inviscid and incompressible flow

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + \frac{\partial p}{\partial x} = 0$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + \frac{\partial p}{\partial y} = 0$$

- In vector form, we have

$$A \frac{\partial U}{\partial x} + B \frac{\partial U}{\partial y} = 0 \quad \text{with } U = \begin{bmatrix} u \\ v \\ p \end{bmatrix} \quad A = \begin{bmatrix} 1 & 0 & 0 \\ u & 0 & 1 \\ 0 & u & 0 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 1 & 0 \\ v & 0 & 0 \\ 0 & v & 1 \end{bmatrix}$$
$$\Rightarrow |T| = -(u n_x + v n_y)(n_x^2 + n_y^2) = 0 \quad \rightarrow \frac{n_x}{n_y} = -\frac{u}{v} \quad \text{and} \quad \frac{n_x}{n_y} = \pm \sqrt{1}$$

- Which means that the equations are of **mixed hyperbolic/elliptic** type.

Linear Unsteady System of Equations

- **EXAMPLE:** Unsteady, 1D, inviscid and compressible flow

$$\begin{aligned}\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + \rho \frac{\partial u}{\partial y} &= 0 \\ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + \frac{1}{\rho} \frac{\partial p}{\partial x} &= 0 \\ \frac{\partial p}{\partial t} + \rho a^2 \frac{\partial u}{\partial x} + u \frac{\partial p}{\partial x} &= 0\end{aligned}$$

- In vector form,

$$\frac{\partial \mathbf{U}}{\partial t} + \mathbf{A} \frac{\partial \mathbf{U}}{\partial x} = 0 \quad \text{with} \quad \mathbf{U} = \begin{bmatrix} \rho \\ u \\ p \end{bmatrix} \quad \mathbf{A} = \begin{bmatrix} u & \rho & 0 \\ 0 & u & 1/\rho \\ 0 & \rho u^2 & u \end{bmatrix}$$

- Whose eigen-values are

$$|\mathbf{A} - \lambda \mathbf{I}| = 0 \quad \rightarrow \quad \lambda = u, u + a, u - a$$

- System has 3 real and distinct eigen-values, therefore, it is **hyperbolic**.

Second order PDEs

- Every second order PDE can be converted to two first order equations first and then dealt with as before.
- **EXAMPLE:** steady, 2D, viscous, incompressible flow

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \\ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{\partial p}{\partial x} + \frac{1}{\text{Re}} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \\ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{\partial p}{\partial y} + \frac{1}{\text{Re}} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \end{array} \right.$$

- **Set,**

$$\left\{ \begin{array}{l} a = \frac{\partial v}{\partial x} \\ b = \frac{\partial v}{\partial y} \\ c = \frac{\partial u}{\partial y} \end{array} \right. \xrightarrow{\text{continuum}} \frac{\partial u}{\partial x} = -\frac{\partial v}{\partial y} = -b$$

Second order PDEs

- In vector form, we get

$$\boxed{A \frac{\partial U}{\partial x} + B \frac{\partial U}{\partial y} = C}$$

$$U = \begin{bmatrix} u \\ v \\ a \\ b \\ c \\ p \end{bmatrix} \quad A = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & \frac{1}{\text{Re}} & 0 & 1 \\ 0 & 0 & \frac{-1}{\text{Re}} & 0 & 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{-1}{\text{Re}} & 0 \\ 0 & 0 & 0 & \frac{-1}{\text{Re}} & 0 & 1 \end{bmatrix}$$

- We get,

$$T = \begin{bmatrix} n_y & 0 & 0 & 0 & 0 & 0 \\ n_x & n_y & 0 & 0 & 0 & 0 \\ 0 & 0 & -n_y & n_x & 0 & 0 \\ 0 & 0 & 0 & n_y & n_x & 0 \\ 0 & 0 & 0 & \frac{n_x}{\text{Re}} & \frac{-n_y}{\text{Re}} & n_x \\ 0 & 0 & \frac{-n_x}{\text{Re}} & \frac{-n_y}{\text{Re}} & 0 & n_y \end{bmatrix} \rightarrow |T| = \frac{1}{\text{Re}} n_y^2 (n_x^2 + n_y^2)^2 = 0 \rightarrow \begin{cases} n_y = 0 \\ \left(\frac{n_y}{n_x}\right)^2 + 1 = 0 \end{cases}$$

- Whose eigen-values are imaginary. Therefore, the system is **mixed elliptic/parabolic**.