

4. (Bonus question: 5 marks) Consider again the signal $x(t)$ in the previous question. What proportion of the total signal power is contained in the frequency range $|\omega| \leq 3\pi$? Recall that Parseval's theorem states that

$$\frac{1}{T} \int_{-T/2}^{T/2} x^2(t) dt = \sum_{k=-\infty}^{\infty} |c_k|^2.$$

$$x(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk(\omega)t} = \dots + c_{-4} e^{-j4\pi t} + c_{-3} e^{-j3\pi t} + c_{-2} e^{-j2\pi t} + c_{-1} e^{-j\pi t} + c_0 + c_1 e^{j\pi t} + c_2 e^{j2\pi t} + c_3 e^{j3\pi t} + c_4 e^{j4\pi t}$$

$$T = 2, \quad c_k = \begin{cases} \frac{1}{2} & k=0 \\ \frac{1}{\pi} \sin\left(\frac{k\pi}{2}\right) & k \neq 0 \end{cases}$$

$$\frac{1}{T} \int x^2(t) dt = \sum_{k=-\infty}^{\infty} |c_k|^2 = \frac{1}{2} \int_{-\pi}^{\pi} 1 dt = \frac{1}{2}$$

$$\begin{aligned} \sum_{k=-3}^3 |c_k|^2 &= \left| \frac{1}{\pi} \sin\left(-\frac{3\pi}{2}\right) \right|^2 + \left| \frac{1}{\pi} \sin\left(-\frac{2\pi}{2}\right) \right|^2 + \left| \frac{1}{\pi} \sin\left(-\frac{\pi}{2}\right) \right|^2 + \left(\frac{1}{2} \right)^2 \\ &\quad + \left| \frac{1}{\pi} \sin\left(\frac{3\pi}{2}\right) \right|^2 + \left| \frac{1}{\pi} \sin\left(\frac{2\pi}{2}\right) \right|^2 + \left| \frac{1}{\pi} \sin\left(\frac{\pi}{2}\right) \right|^2 \\ &= \left(\frac{1}{4} \right) + 2 \left(\frac{1}{9\pi^2} \sin^2\left(\frac{3\pi}{2}\right) \right) + 2 \left(\frac{1}{4\pi^2} \sin^2\left(\pi\right) \right) + 2 \left(\frac{1}{\pi^2} \sin^2\left(\frac{\pi}{2}\right) \right) \\ &= \frac{1}{4} + 2 \left(\frac{1}{9\pi^2} + \frac{1}{\pi^2} \right) = \frac{1}{4} + 2 \left(\frac{10}{9\pi^2} \right) = 0.475 \end{aligned}$$

$$\frac{1}{2} \quad 100 \\ 0.475 \quad \approx 95.03\%$$

۹۵٪ از ایجاد سیگنال در همان گامهایی که مارسون لول خواهد بود است. به همین دلیل است که در اینجا موارد مارسون ها
لا مذکور نیستند.

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مسائل نمونه فصل دوم سیگنال ها و سیستم ها دانشکاه تزیین اسلامی - واحد تهران جنوب
متدهای دینامیکی سیگنال ها و سیستم های مهندسی داده شده باشند

$$h_1(t) = u(t), \quad h_2(t) = -2s(t) + 5e^{-2t}u(t) \quad x(t) = c_3(t) = \text{باخ ملک دارند}$$

$$h_3(t) = 2t e^{-t} u(t)$$

ب) دینامیکی باخ هزبستم LTI دو مرید را بازم ببردی

$$h_1(t) = u(t) \Rightarrow H_1(j\omega) = \frac{1}{j\omega} + 2\delta(\omega)$$

$$x(t) = c_3(t) = \frac{1}{2} e^{jt} + \frac{1}{2} \bar{e}^{jt} \Rightarrow y_1(t) = \frac{1}{2} \left(\frac{1}{j1} \right) e^{jt} + \frac{1}{2} \left(\frac{1}{-j1} \right) \bar{e}^{-jt}$$

$$y_1(t) = \sin(t)$$

$$h_2(t) = -2s(t) + 5e^{-2t}u(t) \Rightarrow H_2(j\omega) = -2 + \frac{5}{2+j\omega}$$

$$x(t) = \frac{1}{2} e^{jt} + \frac{1}{2} \bar{e}^{jt} \Rightarrow y_2(t) = \frac{1}{2} \left(-2 + \frac{5}{2+j1} \right) e^{jt} + \frac{1}{2} \left(-2 + \frac{5}{2-j1} \right) \bar{e}^{-jt}$$

$$= \frac{1}{2} \left(-2 + \frac{5(2-j1)}{5} \right) e^{jt} + \frac{1}{2} \left(-2 + \frac{5(2+j1)}{5} \right) \bar{e}^{-jt}$$

$$y_2(t) = \frac{-j1}{2} e^{jt} + \frac{j1}{2} \bar{e}^{-jt} = \sin(t)$$

$$h_3(t) = 2t e^{-t} u(t) \Rightarrow H_3(j\omega) = \frac{2}{(1+j\omega)^2}$$

$$x(t) = \frac{1}{2} e^{jt} + \frac{1}{2} \bar{e}^{jt} \Rightarrow y_3(t) = \frac{1}{2} \cdot \left(\frac{2}{1+j} \right)^2 e^{jt} + \frac{1}{2} \cdot \left(\frac{2}{1-j} \right)^2 \bar{e}^{-jt}$$

$$= \frac{1}{j2} e^{jt} + \frac{1}{-j2} \bar{e}^{-jt} = \sin(t)$$

$$y_1(t) = h_1(t) * x(t) = \sin(t) \quad y_2(t) = h_2(t) * x(t) = \sin(t), \quad y_3(t) = h_3(t) * x(t) = \sin(t)$$

$$\Rightarrow y_1(t) + y_2(t) = h_1(t) * x(t) + h_2(t) * x(t) = 2 \sin(t)$$

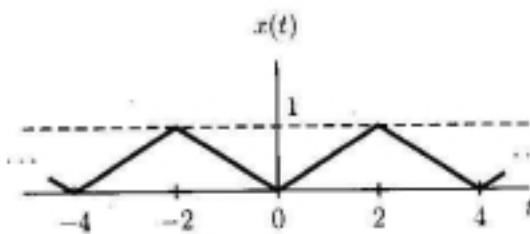
$$\Rightarrow \left(\frac{1}{2} h_1(t) + \frac{1}{2} h_2(t) \right) * x(t) = \sin(t) \Rightarrow h_4(t) = \frac{1}{2} (h_1(t) + h_2(t))$$

$$h_5(t) = \frac{1}{2} (h_1(t) + h_3(t))$$

$$h_6(t) = \frac{1}{2} (h_2(t) + h_3(t))$$

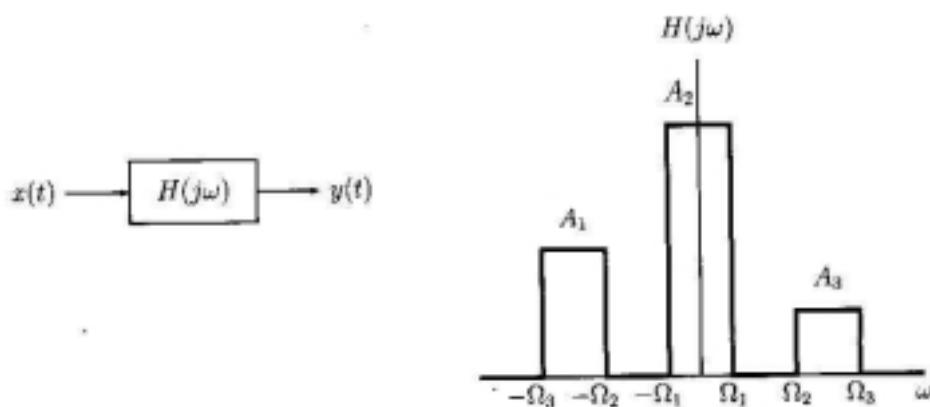
$$h_7(t) = \frac{1}{3} (h_1(t) + h_2(t) + h_3(t))$$

Problem 2 The periodic triangular wave shown below has Fourier series coefficients a_k .



$$a_k = \begin{cases} 2 \frac{\sin(k\pi/2)}{j(k\pi)^2} e^{-jk\pi/2}, & k \neq 0 \\ \frac{1}{2}, & k = 0. \end{cases}$$

Consider the LTI system with frequency response $H(j\omega)$ depicted below:



Determine values of A_1 , A_2 , A_3 , Ω_1 , Ω_2 , and Ω_3 of the LTI filter $H(j\omega)$ such that

$$y(t) = 1 - \cos\left(\frac{3\pi}{2}t\right).$$

$$y(t) = 1 - \frac{1}{2} e^{j\frac{3\pi}{2}t} - \frac{1}{2} e^{-j\frac{3\pi}{2}t} \quad T = 4$$

$$y(t) = 1 - \frac{1}{2} e^{j3(\frac{3\pi}{4})t} - \frac{1}{2} e^{-j3(\frac{3\pi}{4})t} \quad b_0 = 1, \quad b_3 = \frac{-1}{2} \\ b_{-3} = \frac{-1}{2}$$

$$b_0 = a_0 \times H(j0) = \frac{1}{2} \times A_2 = 1 \Rightarrow A_2 = 2$$

$$b_3 = a_3 \cdot H(j3\frac{3\pi}{4}) = a_3 \cdot H(j\frac{3\pi}{2}) = 2 \frac{\sin(\frac{3\pi}{2})}{j(3\pi)^2} \cdot e^{-j\frac{3\pi}{2}} \cdot H(j\frac{3\pi}{2}) = \frac{-1}{2} \\ = \frac{-2}{j(3\pi)^2} \cdot -j \times -1 \times H(j\frac{3\pi}{2}) = \frac{-1}{2}$$

$$H(j\frac{3\pi}{2}) = \frac{(3\pi)^2}{4} = A_3, \quad \Omega_2 < \frac{3\pi}{2} < \Omega_3$$

$$b_{-3} = 2 \frac{\sin(-\frac{3\pi}{2})}{j(-3\pi)^2} \cdot e^{j\frac{3\pi}{2}} \cdot H(-j\frac{3\pi}{2}) = \frac{2}{j(3\pi)^2} \cdot -j \cdot H(-j\frac{3\pi}{2}) = \frac{1}{2} \Rightarrow H(-j\frac{3\pi}{2}) = \frac{(3\pi)^2}{4} = A_1 = \frac{1}{2}$$

$$b_{\pm 1} = 0 \Rightarrow H(\pm j\frac{3\pi}{4}) = 0 \quad \Omega_1 < \frac{3\pi}{4}$$

$$b_{\pm 2} = 0 \Rightarrow H(\pm j\frac{3\pi}{2}) = 0 \quad \Omega_2 > \frac{3\pi}{2}$$

- سیستم LTI نهادن می‌شود که را با ماتریس $H(j\omega)$ در تظریه میری.

$$H(j\omega) = \begin{cases} 1, & |\omega| > 250 \\ 0, & 0 < \omega \leq 250 \end{cases}$$

و حقیقت داده شده این سیستم $x(t) = a_k e^{j\omega_k t}$ باشد. تا داشته باشیم $\frac{\omega}{\omega_0} = T$ و مزایای فوریت a_k است. برای b_k مزایای خوبی خواهد بود. مزایای خوبی خوبه قطعاً صفر است.

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk(\frac{2\pi}{T})t}$$

$$y(t) = \sum_{k=-\infty}^{\infty} a_k \cdot H(jk\frac{2\pi}{T}) \cdot e^{jk(\frac{2\pi}{T})t}$$

$$b_k = a_k \cdot H(jk\omega_0) \quad H(j\omega) = \begin{cases} 1, & |\omega| > 250 \\ 0, & 0 < \omega \leq 250 \end{cases}$$

$$H(jk\omega_0) = \begin{cases} 1, & |k\omega_0| > 250, \quad |k| > \frac{250}{\omega_0} = 17.8 \\ 0, & 0 < k \leq 17 \end{cases}$$

$$H(jk\omega_0) = \begin{cases} 1, & |k\omega_0| > 250, \quad |k| > \frac{250}{\omega_0} = 17.8 \\ 0, & 0 < k \leq 17 \end{cases}$$

$$b_k = 0, \quad |k| \leq 17$$

مسائل نمونه فصل کووم سیگنال ها و سیستم ها دانشگاه آزاد اسلامی - واحد تهران جنوب

- اطلاعات زیر درباره دنباله $x[n]$ داده شده است.

- (a) $x[n]$ is real and odd.
- (b) $x[n]$ is periodic with period $N = 6$.
- (c) $\frac{1}{N} \sum_{n=-N}^{N} |x[n]|^2 = 10$.
- (d) $\sum_{n=-N}^{N} (-1)^{n/3} x[n] = 6j$.
- (e) $x[1] > 0$.

دنباله $x[n]$ متموج یا

که سریع تغییر نماید باید باشد.

$$(a) \Rightarrow a_k \quad \text{مسئله موجود در مر}$$

$$; a_k = \sum_{n=-N}^{N} x[n] e^{-jk\left(\frac{2\pi}{6}\right)n}$$

$$(b) N=6 \Rightarrow a_k = \frac{1}{6} \sum_{n=-6}^{6} x[n] e^{-jk\left(\frac{2\pi}{6}\right)n}$$

$$(c) \frac{1}{6} \sum_{n=-6}^{6} |x[n]|^2 = \sum_{k=-6}^{6} |a_k|^2 = 10$$

$$(d) \sum_{n=-6}^{6} \left(\frac{-j\pi}{6}\right)^{n/3} x[n] = \sum_{n=-6}^{6} e^{-j\frac{\pi}{3}n} x[n] = j6 = 60, \Rightarrow a_1 = j1$$

Problem 3 Consider a causal discrete-time LTI system whose input $x[n]$ and output $y[n]$ are related by the following difference equation:

$$y[n] - \frac{1}{4}y[n-1] = x[n] + 2x[n-4]$$

Find the Fourier series representation of the output $y[n]$ when the input is

$$x[n] = 2 + \sin(\pi n/4) - 2\cos(\pi n/2).$$

$$\begin{aligned} H(j\omega) &= \frac{1+2e^{-j\omega}}{1-\frac{1}{4}e^{j\omega}} \\ x[n] &= 2 + \frac{1}{2j} e^{j\frac{\pi}{4}n} - \frac{1}{2j} e^{-j\frac{\pi}{4}n} - e^{j\frac{\pi}{2}n} - e^{-j\frac{\pi}{2}n} \\ y[n] &= 2 + \frac{3}{4} + \frac{1}{2j} \cdot \frac{1+2e^{-j\pi}}{1-\frac{1}{4}e^{j\frac{3\pi}{4}}} \cdot e^{j\frac{\pi}{4}n} - \frac{1}{2j} \cdot \frac{1+2e^{j\pi}}{1-\frac{1}{4}e^{j\frac{3\pi}{4}}} \cdot e^{-j\frac{3\pi}{4}n} \\ &\quad - \frac{1+2e^{j2\pi}}{1-\frac{1}{4}e^{j\frac{3\pi}{2}}} \cdot e^{-j\frac{3\pi}{2}n} - \frac{1+2e^{j2\pi}}{1-\frac{1}{4}e^{j\frac{3\pi}{2}}} \cdot e^{j\frac{3\pi}{2}n} \\ &= 8 + \frac{1}{2j} \cdot \frac{-1}{1-\frac{1}{4}e^{j\frac{3\pi}{4}}} \cdot e^{j\frac{3\pi}{4}n} - \frac{1}{2j} \cdot \frac{-1}{1-\frac{1}{4}e^{j\frac{3\pi}{4}}} \cdot e^{-j\frac{3\pi}{4}n} \end{aligned}$$